

7 DIGITAL FILTER REALIZATION

Example 7 Compare direct FIR filter realization with overlap-add computation in the frequency domain

Transfer function of FIR filter is

$$H(z) = \sum_{k=0}^9 h(k) z^{-k}, \text{ where } h(k) \in \langle 0,1 \rangle \text{ is random vector}$$

and input vector is random signal $\{x(n), 0 \leq n < 1000\}$

Solution

```
h=rand(1,10);           % generate random transfer function (N2=10)
x=rand(1,1000)         % generate random input function
yr=filter(h,1,x);      % reference computation by filter function
N=32;                  % FFT size used in overlap-add method
y=ola(x,h,N)           % computation by overlap-add method
subplot(2,1,1), plot(yr) % compare results
subplot(2,1,2),
plot(real(y(1:1000))-yr); % note that output y is (in general) complex so real part is taken
% also note that only the first 1000 samples is compared, convolution
% provides (1000+10-1=1009 samples)
```

Questions

What size of FFT is optimal? Try to use different sizes of N .

Is it possible to use this approach for IIR filtration?

Try to approximate IIR filtration by FIR filtration in the frequency domain.

Example 8 Compute state-space representation of IIR filter from Example 1

Solution

```
[b,a,v,u,C]=iirdes('ell','p',[0.1 0.2 0.25 0.3]*pi,0.1,0.001);
[A,B,C,D]=tf2ss(b,a) % compute state space representation
```

Example 9 Show that transformation of the state-space representation by random nonsingular matrix P does not change filter transfer function**Solution**

```
[b,a,v,u,C]=iirdes('ell','p',[0.1 0.2 0.25 0.3]*pi,0.1,0.001);
[A,B,C,D]=tf2ss(b,a) % compute state space representation
P=rand(size(A)) % take random matrix P with the same size as A
det(P) % check that inverse matrix exists – MUST have nonzero determinant!
invP=inv(P) % compute inverse matrix
AA=invP*A*P % find new state-space representation
BB=invP*B
CC=C*P
DD=D
[bb,aa]=ss2tf(AA,BB,CC,DD) % find coefficients of direct form
aa-a % compare differences
bb-b
```